



# OSCAR: Observation System

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Mobile, low-cost, multi-sensors station able to measure the Essential Climate Variables (ECVs)

Sensors	ECVs
Surface meteorological sensors	Temperature, Pressure , Relative Humidity
Rain Gauge	Precipitation
Radiometer (pyranometer)	Solar irradiance at the ground
GPS Antenna receiver	Column water vapor content
Scanning Lidar	Cloud height, fraction, and frequency; profiles of particle optical properties (extinction, backscattering coefficients, LDR)



Vaisala Pressure sensor CS106

Barometer specifications									
Operating range	500 mb to 1100 mb; -40°C to 60°C								
Accuracy	<table border="0"> <tr> <td>±0.3 mb</td> <td>+20°C</td> </tr> <tr> <td>±0.6 mb</td> <td>0°C to +40°C</td> </tr> <tr> <td>±1 mb</td> <td>-20°C to +45°C</td> </tr> <tr> <td>±1.5 mb</td> <td>-40°C to +60°C</td> </tr> </table>	±0.3 mb	+20°C	±0.6 mb	0°C to +40°C	±1 mb	-20°C to +45°C	±1.5 mb	-40°C to +60°C
±0.3 mb	+20°C								
±0.6 mb	0°C to +40°C								
±1 mb	-20°C to +45°C								
±1.5 mb	-40°C to +60°C								
Dimensions	9.7 cm x 6.8 cm x 2.8 cm								
Weight	90 g								



Rotronic T/RH sensor HC2

T/RH probe specifications					
Operating range	-50°C to +60°C; 0% to 100%				
Accuracy	<table border="0"> <tr> <td>±0.1 °C</td> <td>+23°C</td> </tr> <tr> <td>±0.8 %</td> <td>+23°C</td> </tr> </table>	±0.1 °C	+23°C	±0.8 %	+23°C
±0.1 °C	+23°C				
±0.8 %	+23°C				



Vaisala Rain Gauge RG13H

Heated Rain Gauge RG13H Specifications

Property	Description/Value
Sensor/transducer type	Tipping bucket / reed switch
Accuracy	± 1 %
Sensitivity	0.2 mm
Closure time	< 100 ms (for 0.2 mm of rain)
Capacity	Unlimited
Funnel diameter	225 mm
Orifice (opening area)	
standard	400 cm <sup>2</sup>
with expander unit	1000 cm <sup>2</sup>
Max. current rating	500 mA
Breakdown voltage	400 VDC
Capacity open contacts	0.2 pF
Life (operations)	10 <sup>8</sup> closures
Heater	38 W / 40 VDC
Thermostat operation	Opens at +11 °C (±3 °C) Closes at +4 °C (±3 °C)
Material	Non-corrosive aluminum alloy LM25
Dimensions	390 (h) × 300 (Ø) mm
Weight	2.5 kg
Temperature range (operating)	-20 ... +85 °C



## specifications

Spectral range	300 to 2800 nm
Operating range	up to 2000 W/m <sup>2</sup>
Response time	< 12 s
Temperature dependence of sensitivity (-20 °C to +50 °C)	<3%

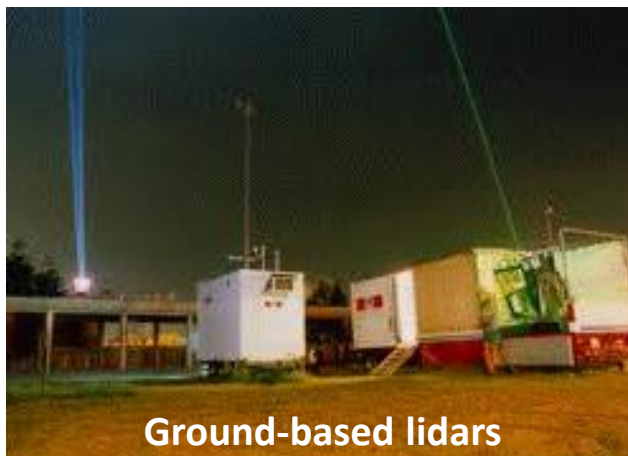
Kipp & Zonen pyranometer SMP3-V

radiant flux, W/m<sup>2</sup>

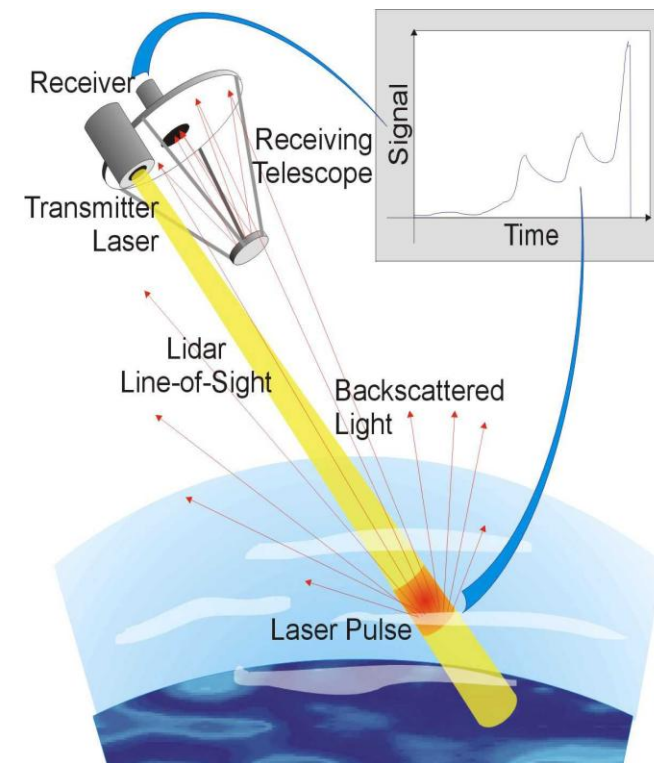


Novatel GPS Antenna SMART6-L

IPWV (Integrated precipitable Water Vapor [cm])



**Lidar (light detection and ranging)** is an active remote sensing techniques which allows to obtain the profiles of the properties of atmospheric constituents, (aerosols, clouds, water vapor, ozone, ..) with high spatial and temporal resolution.



The lidar transmits and receives light pulses ( $\lambda = 250 \div 1100\text{nm}$ )

# OSCAR lidar: transmitter



**Laser head** 3.6kg (8lbs)

**A** 323 mm [12.7"]

**B** 94 mm [3.7"]

**C** 84 mm [3.3"]

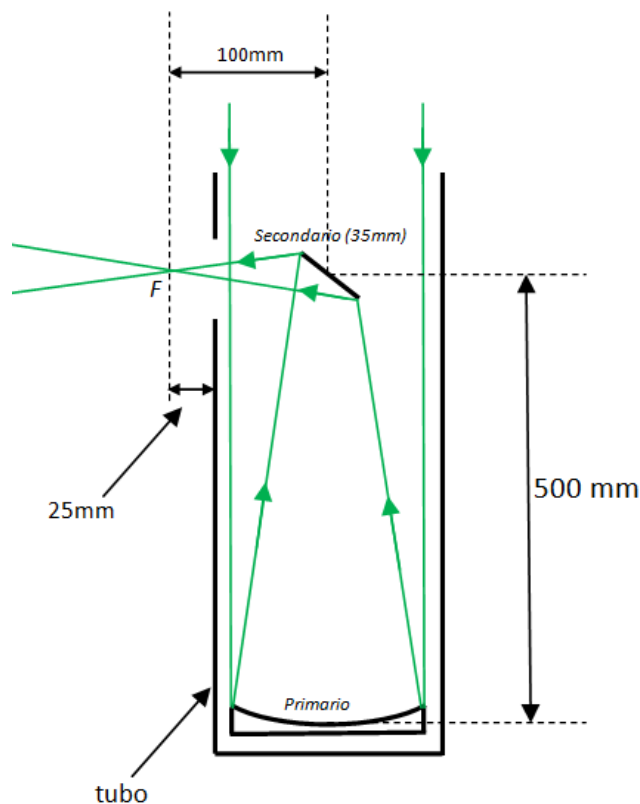


Big Sky Laser - CFR 200  
Quantel

Transmitter	
Pulsed laser Source	Nd:YAG
Laser Class	IV
Wavelength	532 nm
Energy per Pulse	130 mJ
Repetition Rate	20Hz
Laser Beam Diameter (Near Field)	< 6.35mm
Laser Beam Divergence (Full Angle)	< 4 mrad
Beam Expander	5 X
Beam Divergence	< 0.8 mrad



# OSCAR lidar: receiver



TS UNC1506 telescope

## Receiver technical features

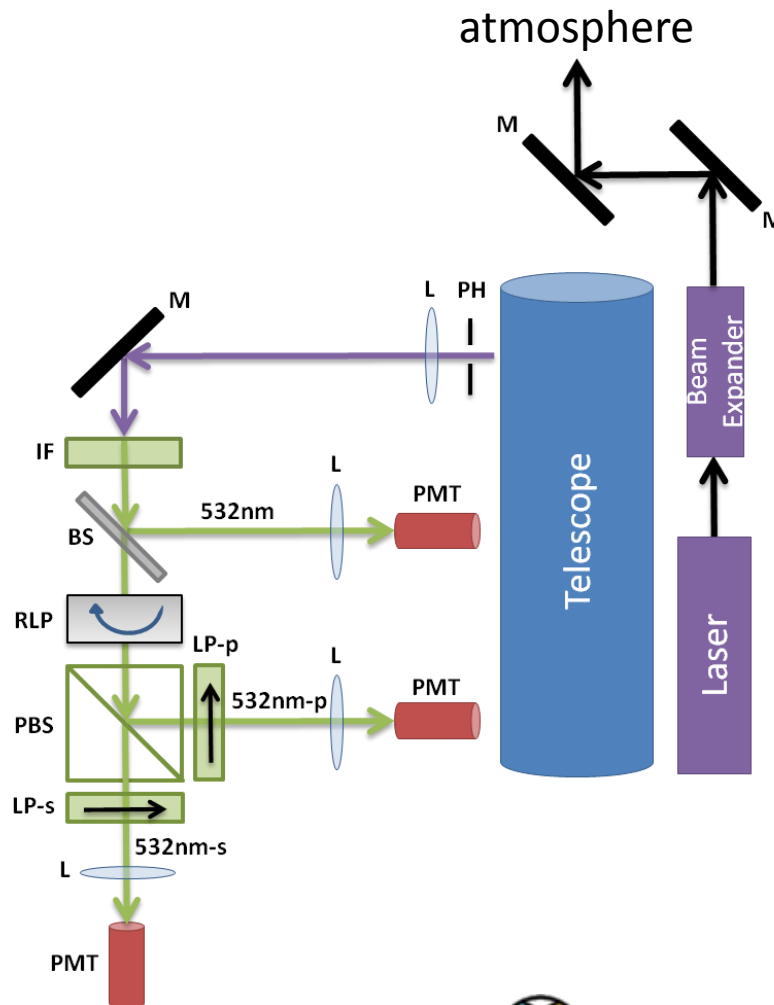
Telescope configuration	Newton
Primary Mirror Diameter	150 mm
Major Axis of Secondary Mirror	49.5 mm
Minor Axis of Secondary Mirror	35 mm
Distance of F from the tube	25 mm
Distance of F from the secondary mirror	100 mm
Focal length	600 mm
F/ Number	F/4
Field of View	2.5 mrad (tunable from 1.5 to 3mrad)
Weight	4 Kg

# OSCAR lidar: optical layout



**Legend:**

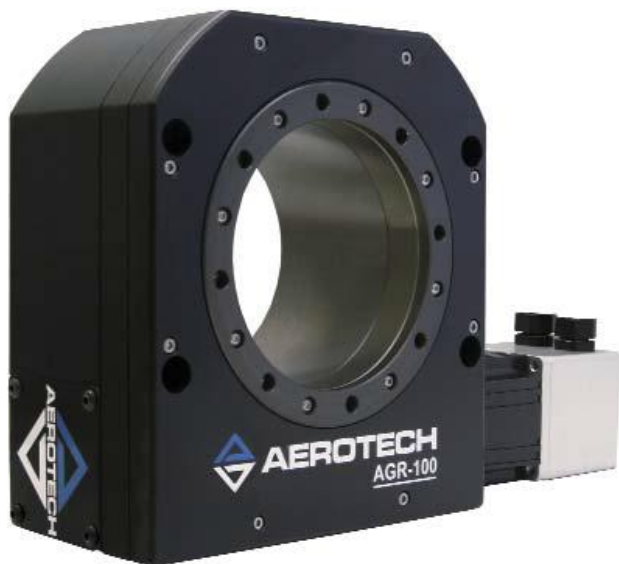
- M:** Mirror
- PH:** Pin Hole
- L:** Lens
- IF:** Interferential Filter
- BS:** Beam Splitter
- RLP:** Rotating Linear Polarizer
- PBS:** Polarizing Beam Splitter
- LP-s:** Linear polarizer: cross component
- LP-p:** Linear polarizer: parallel component
- PMT:** photomultiplier



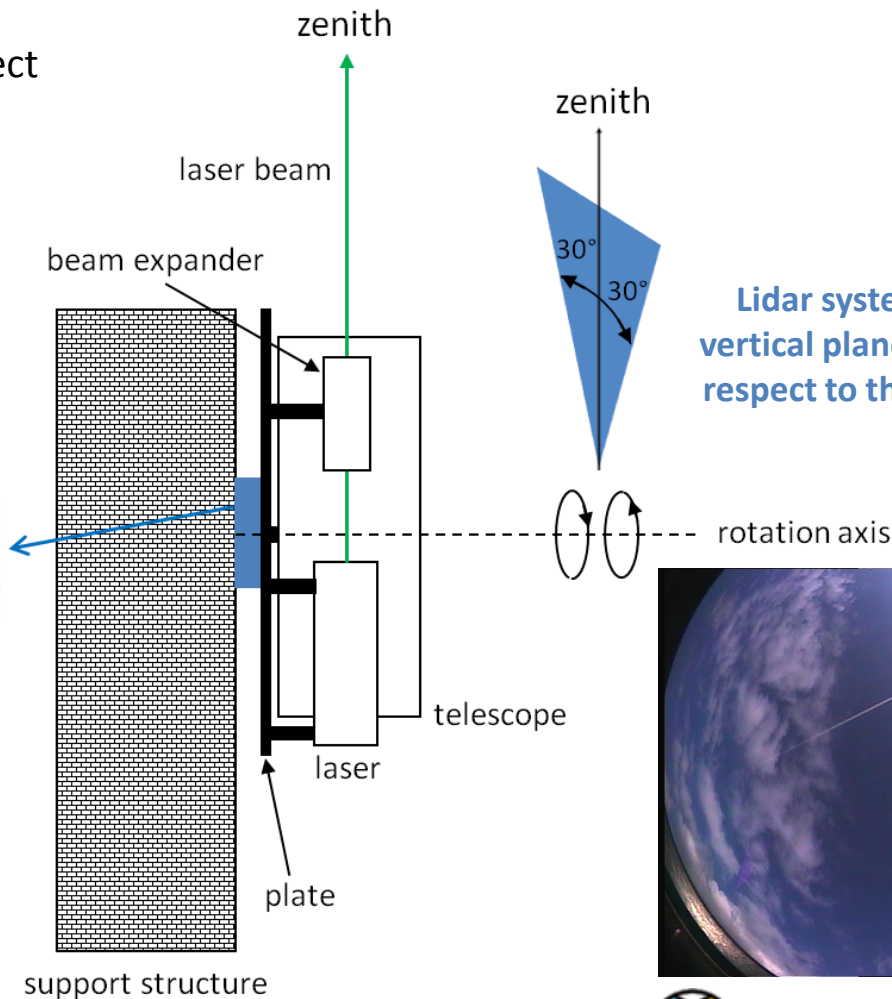
# OSCAR lidar: steering unit



rotary stage AGR 100 – BMS with Direct Encoder

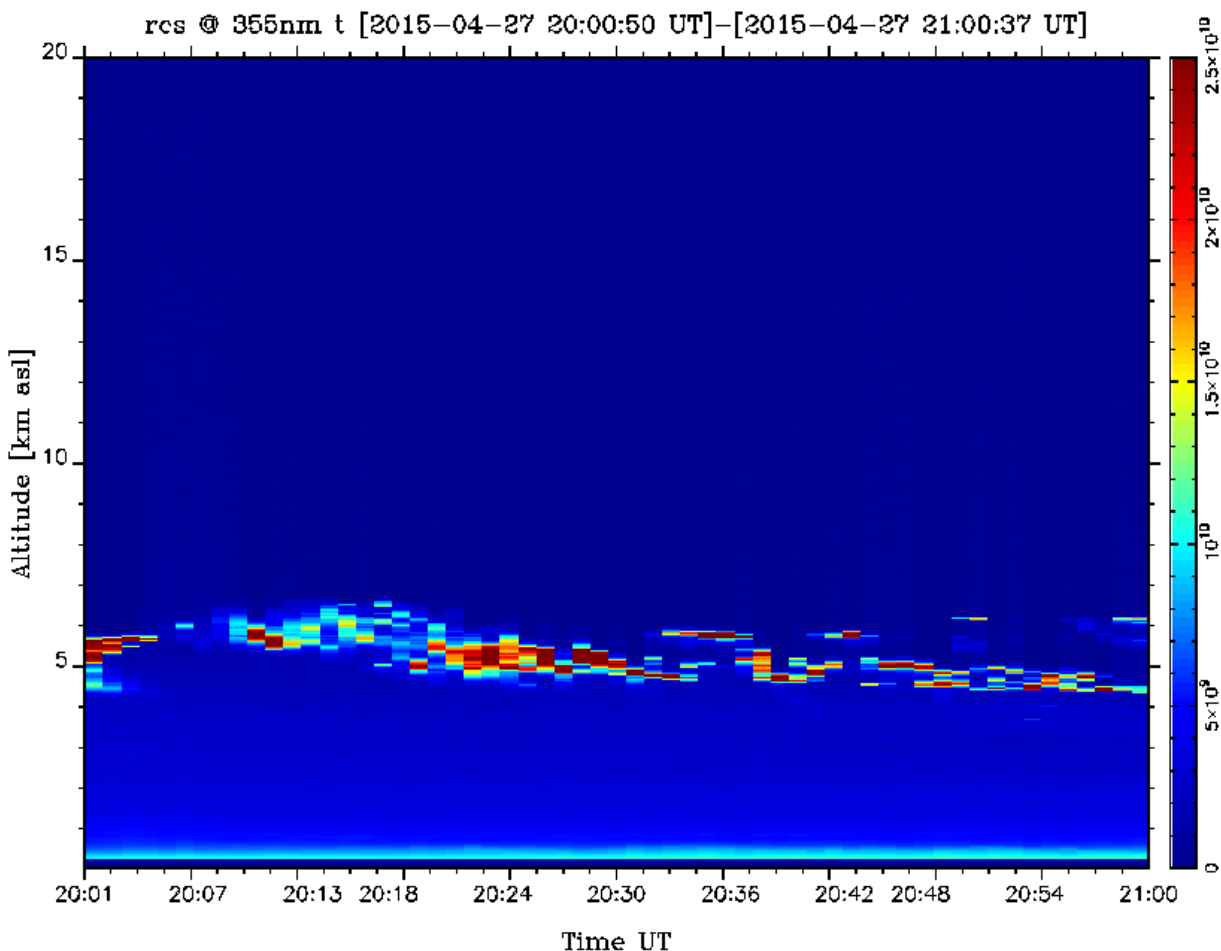


Accuracy:  $20'' = 1/180^\circ$   
Maximum speed:  $180^\circ/s$



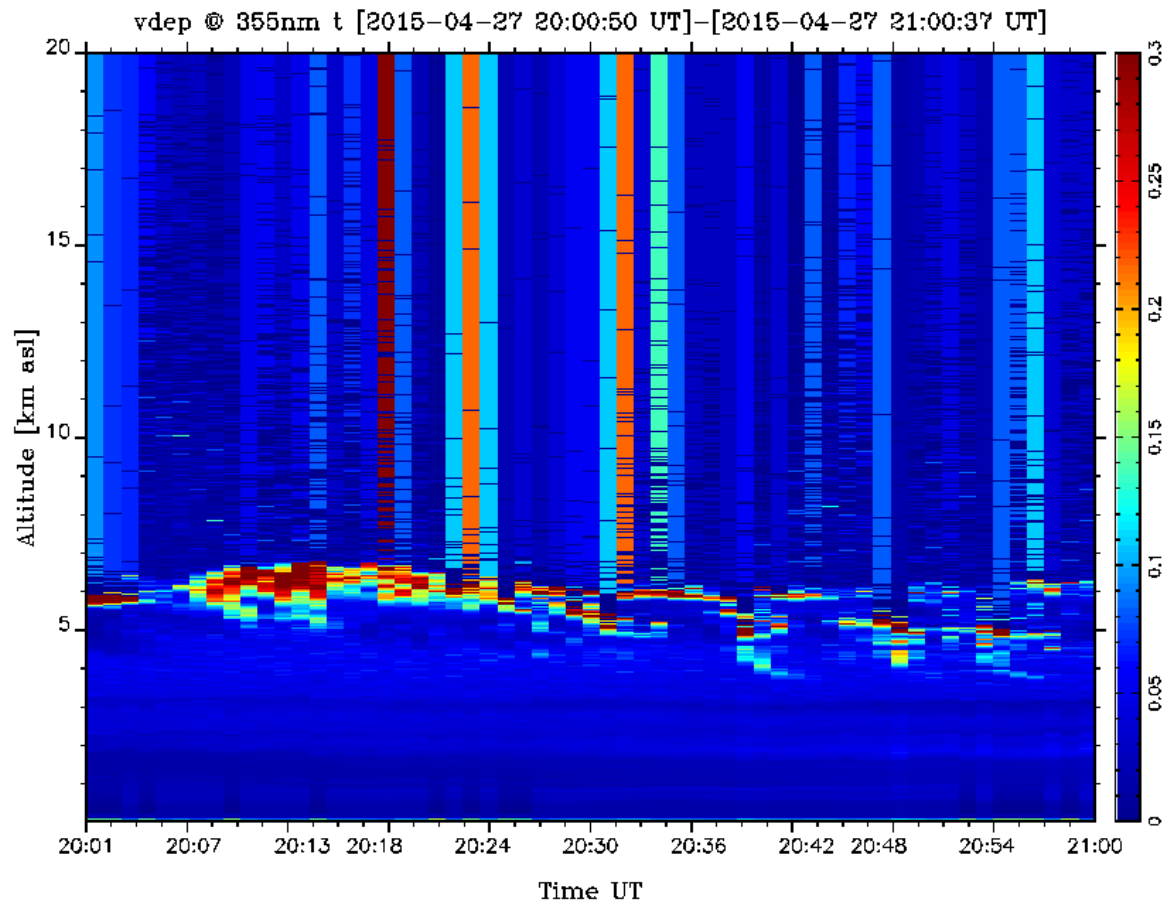
Lidar system rotating on a vertical plane within  $\pm 30^\circ$  with respect to the zenith direction



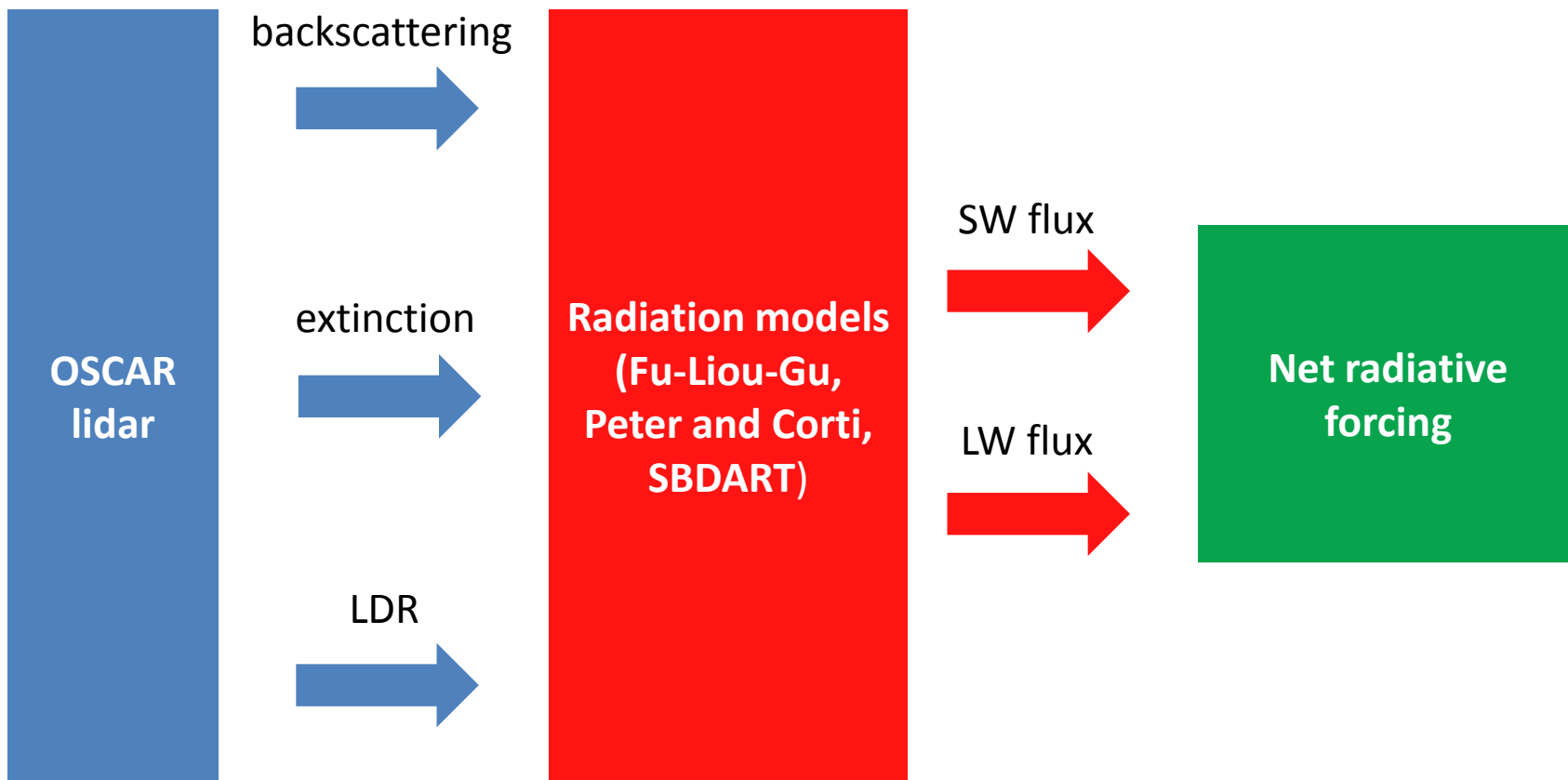


- lidar signals:**
- ✓ cloud identification, height, fraction and frequency
  
  - ✓ Profiles of particle backscattering and extinction coefficients

# OSCAR lidar: products



**lidar signals:**  
 ✓ Profiles of linear  
 depolarization ratio (LDR)





# Thanks for your attention!

